

# Dwell Adaptive Fragmentation : how to cope with short dwells required by multimedia wireless LANs

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*This paper studies the impact on CSMA/CA traffic of a reduction of the dwell size, a fundamental parameter of some wireless LANs. First, we explain why we want to reduce the dwell size and what are the consequences. Then, we present some ways to overcome the overhead of short dwell, mostly based on fragmentation. We finish by some exhaustive simulations of the short dwell size impact and variations, and the way those fragmentation schemes improve the network performance.*

## 1 Introduction

Designing a radio MAC protocol is always a game of tradeoff. The MAC layer is trying to interface the network layer on top of the radio physical layer, and the requirements of these are often conflicting.

When it comes to some essential parameters of the MAC protocol, there is no absolute answer and each designer has to set them according to the constraints, traffic patterns, operating environment conditions and the results of simulations.

The dwell time is one of those parameters, where the radio constraints invite for a small value but network traffic prefers a large value, and the MAC designer has to compromise...

## 2 Reason for short dwell

The dwell time is a concept typically unknown in wired networks and applies only to some wireless LANs.

### 2.1 Dwell time

The Dwell time is mainly a characteristic of Frequency Hopping systems [1]. Frequency Hopping is a technique to increase the system reliability (by introducing frequency diversity to mitigate the impact of channel errors) and to limit and regulate usage of the spectrum (by forcing different independent systems to share the bandwidth).

The system uses a set of frequencies for transmissions and cycle through them periodically. Common systems use a fixed hopping rate and a fixed hopping pattern.

Consequently, the system stays only a limited fixed time on each frequency before hopping to the next frequency in the sequence. The time between two hops is linked to the hopping rate and called the Dwell time.

### 2.2 Increasing the hopping rate

Hopping faster (reducing the dwell size) doesn't much increase the reliability of the MAC: as the number of channels is limited the probability of hitting a bad channel and losing a packet remains the same. But, if we could manage to send each MAC level retransmission of a packet on a different channel, we would extract maximum benefit from the frequency diversity given by frequency hopping.

More importantly, this reduction of dwell size allows to decrease the latency of the system: the system stays a shorter time on the bad channels, where transmissions may be blocked [6], and move more quickly to a good one.

Decreasing the latency helps with TCP congestion control algorithm and for multimedia applications.

### 2.3 Isochronous traffic

The other reason to have short dwell is when the system supports isochronous traffic. The delay requirements for isochronous traffic are usually too tight to enable this traffic over standard CSMA/CA, and this traffic is sent in a special frame [3]. The CSMA/CA traffic occurs only between these isochronous frames, in what we can call a dwell.

To optimise the isochronous node operations (guarantee of delay, codec synchronisation, power saving...), this frame must come at fixed regular interval [2] and this interval be short (typically 10 to 20 ms).

## 3 Impact of short dwell

The natural tendency for systems having a dwell is to reduce its size, because of the benefits that it brings. However, this is not without drawbacks...

### 3.1 Lost time at the end of a dwell

The most common effect of having a short dwell on CSMA/CA is the reduction in performance. The time between the end of a dwell and the start of the next one can't be used for transmission. But it's either a hop, and in most case very short (around 250  $\mu$ s), or it is isochronous traffic, so useful to the system.

However, the main reduction of performance is not so much the time between the two dwells, but the time lost at the end of each dwell due to the granularity of the transmissions. Each transmission must fit entirely within the dwell, so if the time remaining before the end of dwell is shorter than the transmission time of the packet to send, the packet has to wait for the next dwell and this time is lost (see fig. 3.1).

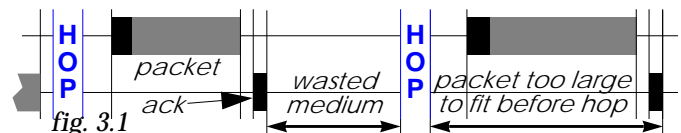


fig. 3.1

This overhead is sometimes increased because some implementations use crude approximation to make this comparison (coarse timers, assume all packets are of maximum size) or some protocols have non predictable packet transmission time (HDLC stuffing provides an expansion factor between 0 and 5 % difficult to estimate).

### 3.2 Dwell size and packet size

One simple solution would be to adapt the dwell size to the packet size or vice versa. This is usually not possible.

The hopping rate is usually constrained by the requirement of the isochronous traffic (latency) and fixed. Moreover, isochronous traffic has precedence over CSMA/CA, so the dwell size available to CSMA/CA depends on the current isochronous traffic requirement and may vary in time.

Packets sizes and their distributions are usually fixed by the applications and the MAC has little control over this. This alone prevents hardcoded optimisation between dwell size and packet size (see section 6.2).

### 3.3 Blocked packets

If the dwell is too short, it is possible that it is not long enough to carry out the transmission of the largest CSMA/CA packets. In that case, these large packets can't be transmitted at all, blocking the transmitter (unless there is a timeout).

Of course, no MAC designer would design a MAC having such a short dwell, but as mentioned above, an increase of the isochronous traffic may reduce the dwell size, so this case may happen when there is too many isochronous connections.

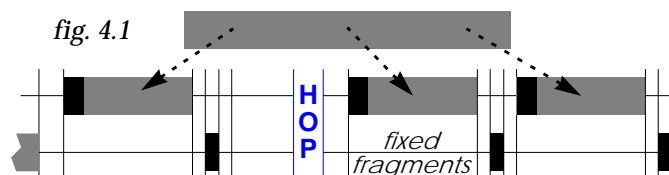
## 4 Remedies : fragmentation

When the dwell become shorter, the time lost at the end of the dwell may become a very significant overhead (see section 6.1), and packets blocked are definitely to avoid.

### 4.1 Fixed fragmentation

The main reason for these problems is the granularity of the transmissions within the dwell. The logical way to overcome this is to reduce the transmission time. As the packet sizes are not under our control, we need to use fragmentation at the link layer.

802.11 offers an efficient fragmentation scheme [1], designed to reduce the impact of channel errors. Fragments are of fixed size and sent in a contention free frame, the receiver automatically performing the reassembly of the original packet (see fig. 4.1).



A typical implementation (like my model) would use a fixed threshold and split a packet evenly in fragments smaller than the fragmentation threshold.

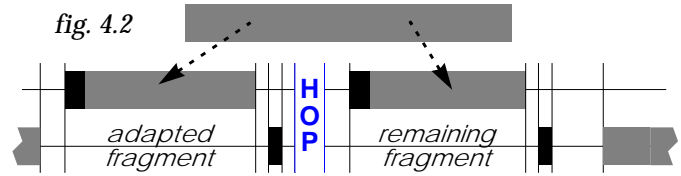
Fragments, because they are smaller, fit better in the dwell, so can use more efficiently the time at the end of the dwell and avoid being blocked. On the other hand, fragmentation adds a significant overhead (a header and an ack transmission for each fragment - see section 7.1).

### 4.2 Dwell adaptive fragmentation

One of the main drawbacks of the 802.11 fragmentation scheme is that the size of the fragments needs to be fixed in advance and cannot change. We would like to fragment

packets only when necessary (to fit in the dwell) and keep them unfragmented otherwise (to minimise the overhead).

In fact, there is no reason why we can't do that. The sender can choose on the fly prior to transmission the ideal fragment size (allowing the fragment to fit perfectly in the remaining dwell) and changing the fragment size in case of retransmission (see fig. 4.2).



The only magic is in the receiver implementation : it must always replace an old fragment in favor of a retransmission of it and keep two pointers in the received buffer, one on the last byte received (for receiving a new fragment) and one on the beginning of the last fragment received (for replacing it).

The transmitter would use 3 parameters to control the adaptive fragmentation scheme : the *fragment threshold* (maximum size of fragments), the *minimum adapted fragment size* (minimum size of fragments it can create) and the *minimum remaining fragment size* (minimum size of the last fragment). The *minimum adapted fragment size* prevents creating ridiculously small fragments (which are inefficient) and allows to leave the last part of the dwell reserved for small packets (which improves performance - see section 6.6).

### 4.3 Multicast packets

One of the disadvantages of the fragmentation schemes presented is that they apply only to unicast packets. It is possible to design a fragmentation scheme for multicast packets, but it doesn't make sense in practice. This scheme would be needlessly complex and very unreliable : all fragments would need to be received error free first time to be reassembled (no retransmissions possible on multicast packets), so the probability of losing a fragmented multicast increases exponentially with the number of fragments.

As multicast transmissions are less used and usually not performance critical, we can tolerate the overhead they have. However, the prospect of packets blocked is not welcomed. But we can't use fragmentation, and most networking stacks doesn't allow to set a maximum packet size (MTU) different for multicast packets than unicast packets.

In fact, if the case arises when the full dwell can't accommodate a multicast packet, the only practical solution would be to simply drop the multicast packet ! Multicast transmissions have never been reliable on wireless protocol [5], so this would be no big surprise for most applications...

## 5 Simulation model

The models used for these simulations have been carefully chosen to be simple and realistic, and to illustrate the impact of small dwell and adaptive fragmentation.

### 5.1 MAC model

The MAC model includes a fairly complete 802.11 channel access mechanism. This model is based on an 802.11

backoff (slotted exponential contention). All management functionalities have been removed to keep the model simple.

The model implements MAC level acknowledgments and retransmissions. When stated, the model includes RTS/CTS (for packets larger than 250 B), fragmentation or adaptive fragmentation.

By default, the maximum packet size is 1500 B. All other defaults parameters conform to 802.11 [1] (CW<sub>min</sub> = 16 ; SIFS = 28  $\mu$ s ; Slot = 50  $\mu$ s ; Hop delay = 224  $\mu$ s ; Headers = 50 B ; Ack/RTS/CTS = 30 B ; MaxRetries = 7). Some simulations use different values for some of those parameters.

## 5.2 Channel model

The channel model is a simple radio channel model, including node to node attenuation (80 dB by default), Rayleigh fading (calculated on a per packet basis) and antenna diversity. The bit rate is 2 Mb/s, and there are no hidden nodes and no interferers. The transmitted power is +20 dBm, and the sensitivity is -80 dBm (in a Gaussian channel).

## 5.3 Traffic models

Various traffic models are used through the simulations. More information on the traffic models and their behaviour may be found in my previous papers [4].

### 5.3.1 Random traffic model

The *random* traffic model generates packets following a Poisson process (random interarrival time with negative exponential distribution) and all packet sizes are uniformly distributed in  $[0 ; \text{max packet size}]$ .

### 5.3.2 TCP2 traffic model

The *TCP2* traffic model is a simple bimodal distribution to simulate TCP traffic. Each packet is either big (maximum size) or small (40 B), the probability of being small is 1/2. Packets are sent as fast as the link can manage.

### 5.3.3 TCP1 traffic model

The *TCP1* traffic model simulates a node sending a large amount of data over a protocol such as TCP. The sender sends packets of the maximum size as fast as possible.

The receiving node acknowledges incoming packets with short packets (40 B). The probability of small packet is 1/3 (the receiver sends a small packet for each received packet with a probability 1/2).

## 6 Dwell overhead : simulation results

Many simulations have been performed to study the impact of the dwell size variations and how fragmentations and adaptive fragmentation can cope with that. All the simulations have been implemented under the Bones® Designer™ environment.

### 6.1 Impact of traffic model

In this simulation, we use 3 different traffic models and network setups. The first system simulates a TCP transfer between two nodes using the *TCP1* model, the second system is 5 nodes sending TCP traffic using the *TCP2* model and the third system is 10 nodes using the *random* traffic.

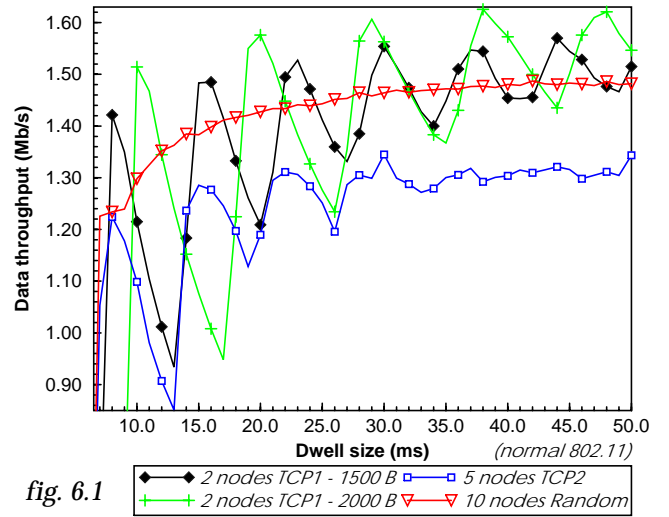


fig. 6.1

The **2 nodes TCP1** system is the most sensitive to dwell size variations (see fig. 6.1). The curve shows clearly the dwell size where we can fit one 1500 B packet, and then two, and three, and that the increase of the dwell decreases performance until we can fit one more packet in it (because of the time wasted at the end of it). The curve also shows that below 8 ms the packets are simply blocked.

On the other hand, the **10 nodes random** system is much less sensitive to dwell size. Having a larger number of transmitters and random distribution of packet size give a high probability of having one node who has a short packet that can fit in the time before the end of the dwell. In this case, the main overhead is the hop time itself.

The **5 nodes TCP2** system is also quite sensitive to the dwell size, due to the large number of large packets.

### 6.2 Impact of packet sizes

Changing the packet size affects how packets fit in the dwell (see section 3.2). With larger packets (2000 B instead of 1500 B), the impact of the dwell overhead on the **2 nodes TCP1** system is increased (higher jitter), as well as the dwell size where packets are blocked (see fig. 6.1).

### 6.3 Impact of contention slot size

The size of the contention period is an important performance factor in most MAC protocols [4]. The size of the contention slot, like the size of the SIFS, is mainly governed by the physical layer *RxTxTurnaround* time. 802.11 uses 20  $\mu$ s, SWAP uses 34  $\mu$ s, Proxim OpenAir uses around 200  $\mu$ s and we can expect 100  $\mu$ s from DECT chipset.

To illustrate that effect, we simulate the **2 nodes TCP1** system with the normal 20  $\mu$ s *RxTxTurnaround* time and with 100  $\mu$ s (see fig. 6.3). Increasing the *RxTxTurnaround* time has of course a negative impact on CSMA/CA performance, because it makes contention longer. The only effect with regards to dwell overhead is to move the curve horizontally, because with an increased *RxTxTurnaround* time the dwell needs to be larger to fit the same number of packets.

### 6.4 Impact of header size

The size of the header may also impact the performance of the MAC [4]. 802.11 uses 50 B headers, SWAP uses only

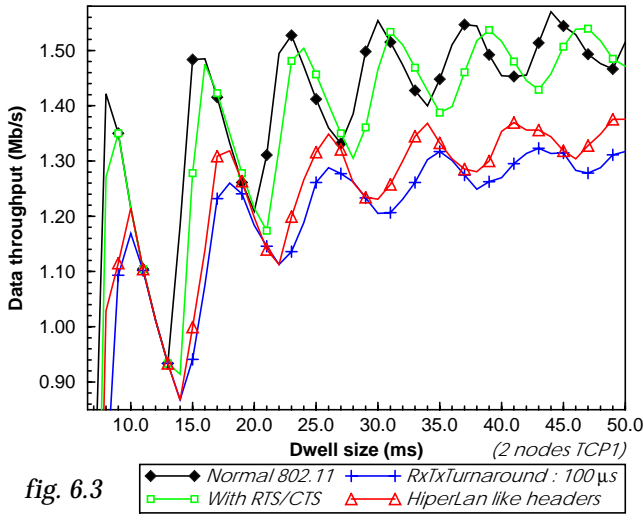


fig. 6.3

37 B, whereas HiperLan use the equivalent of 186 B (including low bit rate and training sequence).

In this simulation we compare the 802.11 overhead with the HiperLan overhead for a **2 nodes TCP1** system (see fig. 6.3). Increasing the header size has globally the same effect as increasing the *RxTxTurnaround* time, lowering the throughput and shifting the curve to higher dwell.

### 6.5 Impact of RTS/CTS

The use of RTS/CTS also has an impact on the performance of the MAC protocol. RTS/CTS adds the overhead of the RTS/CTS handshake before every packet, making the transmission longer.

Again, this shifts the curve to higher dwell (see fig. 6.3). However, as opposed to the increase in slot size or header size, the performance with RTS/CTS may be higher than the normal system because RTS/CTS reduces collision penalty.

### 6.6 Latency differences

Probably the most interesting effect of a short dwell is on the latency of small and large packets.

A limited dwell size means that often large packets are postponed from one dwell to the next, because the remaining time is too short for their transmission. The net effect is that the latency of those packets is increased.

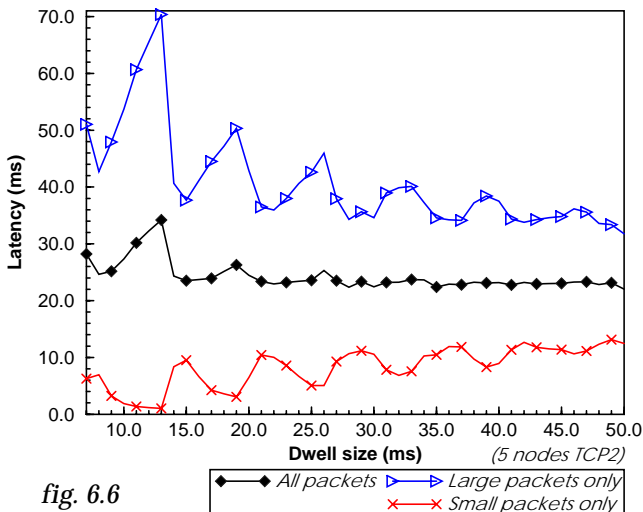


fig. 6.6

However, for small packets, the situation is different. These packets can usually fit perfectly in the end of the dwell. In fact, because big packets are postponed, the bandwidth at the end of each dwell is like “reserved” for them.

In this simulation, we compare the average latency of small and large packets for the **5 nodes TCP2** system (see fig. 6.6). With the reduction of dwell size, the latency of large packets tend to increase (matching the throughput curve) while the latency of small packets can be very close to 0 ms.

## 7 Fragmentations : simulation results

The previous section (see section 6) has shown what is the impact of short dwell on CSMA/CA. To mitigate this effect, fragmentation seems the most practical solution (see section 4). The following simulations explore the benefits of fragmentation.

### 7.1 Fixed fragmentation

By default, 802.11 offers only fixed fragmentation. In this simulation, we explore the impact of different fragment threshold on the **2 nodes TCP1** system, which corresponds to separating the packet in 1, 2, 3 and 6 fragments.

Reducing the fragment size reduces dramatically the impact of the jitter (see fig. 7.1), and the smallest fragment size offer a very smooth curve. On the other hand, we can see that fragmentation carries a significant overhead.

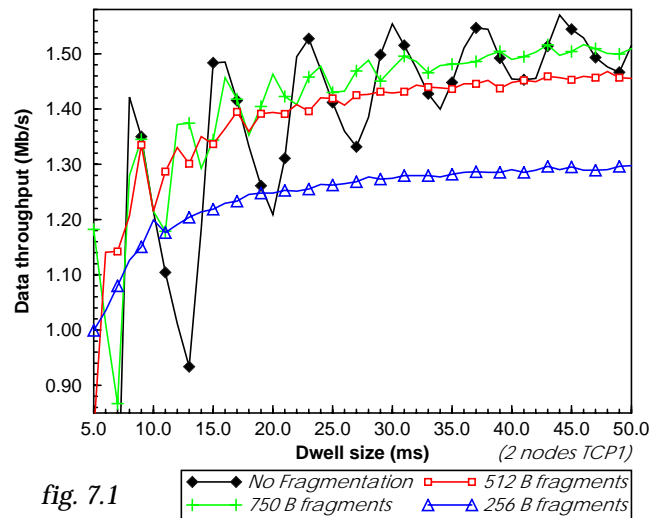


fig. 7.1

In fact, for each dwell size, there is an optimal fragment size which gives a good tradeoff between the reduction in jitter and reduction of throughput. For example for SWAP [2] we have chosen a fragment threshold of 512 B at 1 Mb/s and 1024 B at 2 Mb/s (SWAP has a 20 ms dwell, 1 Mb/s is almost equivalent to a 10 ms dwell in those simulations).

### 7.2 Dwell adaptive fragmentation - TCP1

The dwell adaptive fragmentation scheme fragments packets only when necessary and tailors the packets to the space available in the dwell.

To verify the impact of dwell adaptive fragmentation, two additional **2 nodes TCP1** systems are simulated. The first one has a *fragment threshold* of 1500 B and a *minimum adapted fragment size* of 256 B, so it fragments packets only when



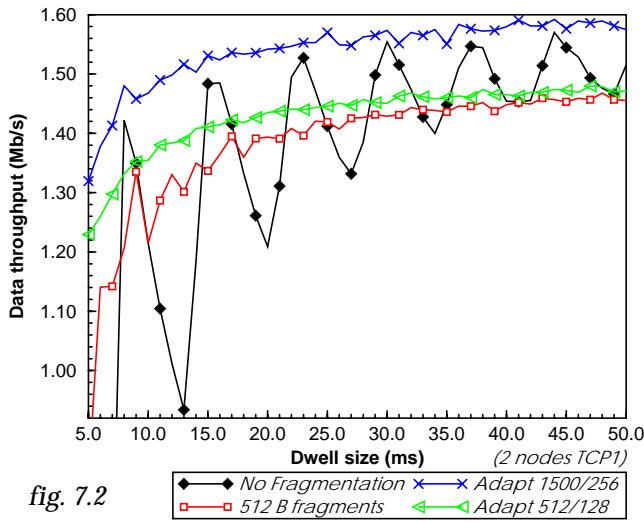


fig. 7.2

needed and can leave space for 2 small packets at the end of the dwell. The second one has a *fragment threshold* of 512 B and *minimum adapted fragment size* of 128 B, so fragments packets in 512 B fragments or smaller. In both case the *minimum remaining fragment size* is 0 B. Those systems are compared to fixed fragmentation with 1500 B and 512 B fragment threshold.

Dwell adaptive fragmentation almost totally removes the jitter produced by short dwell size (see fig. 7.2) and provides a substantial performance enhancement for short dwell. Dwell adaptive fragmentation with maximum fragment threshold always outperform other schemes, so the fragment threshold no longer needs to be tuned to the dwell size.

In fact, dwell adaptive fragmentation almost totally removes the overhead of small dwell (apart from the hop time itself and the fragmentation overhead).

### 7.3 Adaptive fragmentation - TCP2

The same simulation setup as in the previous section is used, but using **5 nodes TCP2** systems and RTS/CTS.

In this simulation, the improvement offered by fragmentation and adaptive fragmentation is slightly smaller (see fig. 7.3a), because the impact of short dwell was smaller to start with (more nodes and more small packets). But adaptive fragmentation still outperform other schemes.

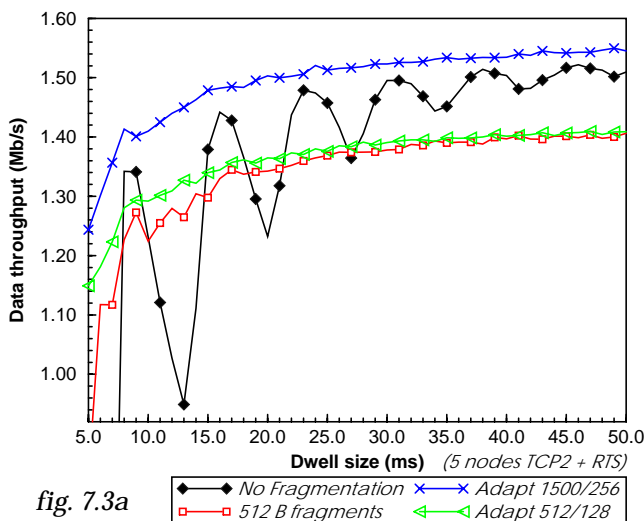


fig. 7.3a

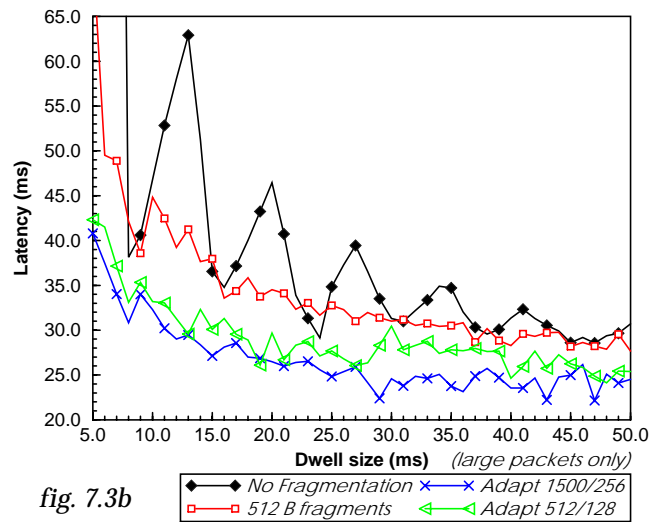


fig. 7.3b

As we can guess, fragmentation has also an impact on the latency of the system. Short dwell has a tendency to increase the latency of large packets. To verify the impact of fragmentation, the latency of large packets for the **5 nodes TCP2** system in the same setup is measured (see fig. 7.3b). Adaptive fragmentation removes most of the jitter and offers a nice reduction of the latency for large packets.

## 8 Conclusions

Increasing the hopping rate allows frequency hopping systems to better exploit frequency diversity and reduce transmission latency. Isochronous transmissions require a short dwell as well. But large CSMA/CA transmissions can't use efficiently the time of the end of the dwell, just before the hop, and in many case this time is wasted (no transmissions).

When the dwell is short, this wasted time becomes very significant. Fixed fragmentation with a judicious choice of the fragment threshold allows to reduce this overhead. Dwell adaptive fragmentation adds only a little more complexity to fixed fragmentation but increase significantly the performance of the system and is much more versatile.

## 9 References

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